

Solving Symmetric Semi-definite (ill-conditioned) Generalized Eigenvalue Problems

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Symmetric definite generalized eigenvalue problem

- ▶ Symmetric definite generalized eigenvalue problem

$$Ax = \lambda Bx$$

where

$$A^T = A \quad \text{and} \quad B^T = B > 0$$

- ▶ Eigen-decomposition

$$AX = BX\Lambda$$

where

$$\Lambda = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$$

$$X = (x_1, x_2, \dots, x_n)$$

$$X^T B X = I.$$

- ▶ Assume $\lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_n$

LAPACK solvers

- ▶ LAPACK routines `xSYGV`, `xSYGVD`, `xSYGVX` are based on the following algorithm (Wilkinson'65):

1. compute the Cholesky factorization $B = GG^T$
2. compute $C = G^{-1}AG^{-T}$
3. compute symmetric eigen-decomposition $Q^T C Q = A$
4. set $X = G^{-T}Q$

- ▶ `xSYGV[D,X]` could be *numerically unstable* if B is ill-conditioned:

$$|\hat{\lambda}_i - \lambda_i| \lesssim p(n)(\|B^{-1}\|_2 \|A\|_2 + \text{cond}(B)|\hat{\lambda}_i|) \cdot \epsilon$$

and

$$\theta(\hat{x}_i, x_i) \lesssim p(n) \frac{\|B^{-1}\|_2 \|A\|_2 (\text{cond}(B))^{1/2} + \text{cond}(B)|\hat{\lambda}_i|}{\text{specgap}_i} \cdot \epsilon$$

- ▶ User's choice between the inversion of ill-conditioned Cholesky decomposition and the QZ algorithm that destroys symmetry

Algorithms to address the ill-conditioning

1. Fix-Heiberger'72 (Parlett'80): explicit reduction
2. Chang-Chung Chang'74: SQZ method (QZ by Moler and Stewart'73)
3. Bunse-Gerstner'84: MDR method
4. Chandrasekaran'00: "proper pivoting scheme"
5. Davies-Higham-Tisseur'01: Cholesky+Jacobi
6. Working notes by Kahan'11 and Moler'14

This talk

Three approaches:

1. A LAPACK-style implementation of Fix-Heiberger algorithm
2. An algebraic reformulation
3. Locally accelerated block preconditioned steepest descent (LABPSD)

This talk

Three approaches:

1. A LAPACK-style implementation of Fix-Heiberger algorithm
Status: beta-release
2. An algebraic reformulation
Status: completed basic theory and proof-of-concept
3. Locally accelerated block preconditioned steepest descent (LABPSD)
Status: published two manuscripts, software to be released

A LAPACK-style implementation of Fix-Heiberger algorithm (with C. Jiang)

A LAPACK-style solver

- ▶ **xSYGVIC**: computes ε -stable eigenpairs when $B^T = B \geq 0$ wrt a prescribed threshold ε .
- ▶ Implementation is based on Fix-Heiberger's algorithm, and organized in three phases.
- ▶ Given the threshold ε , **xSYGVIC** determines:
 1. $A - \lambda B$ is regular and has k ($0 \leq k \leq n$) ε -stable eigenvalues **or**
 2. $A - \lambda B$ is singular.
- ▶ The new routine **xSYGVIC** has the following calling sequence:

```
xSYGVIC( ITYPE, JOBZ, UPLO, N, A, LDA, B, LDB, ETOL, &  
         K, W, WORK, LDWORK, WORK2, LWORK2, IWORK, INFO )
```


xSYGVIC – Phase I

1. Compute the eigenvalue decomposition of B (xSYEV):

$$B^{(0)} = Q_1^T B Q_1 = D = \begin{matrix} n_1 & n_2 \\ n_2 & \end{matrix} \begin{bmatrix} D^{(0)} & \\ & E^{(0)} \end{bmatrix},$$

where diagonal entries of D : $d_{11} \geq d_{22} \geq \dots \geq d_{nn}$, and elements of $E^{(0)}$ are smaller than $\varepsilon d_{11}^{(0)}$.

2. Set $E^{(0)} = 0$, and update A and $B^{(0)}$:

$$A^{(1)} = R_1^T Q_1^T A Q_1 R_1 = \begin{matrix} n_1 & n_2 \\ n_2 & \end{matrix} \begin{bmatrix} A_{11}^{(1)} & A_{12}^{(1)} \\ A_{12}^{(1)T} & A_{22}^{(1)} \end{bmatrix}$$

and

$$B^{(1)} = R_1^T B^{(0)} R_1 = \begin{matrix} n_1 & n_2 \\ n_2 & \end{matrix} \begin{bmatrix} I & \\ & 0 \end{bmatrix},$$

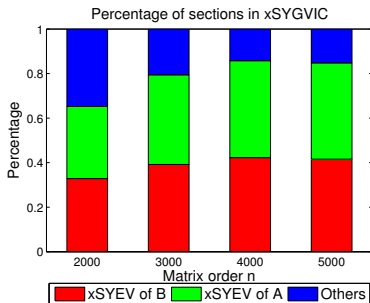
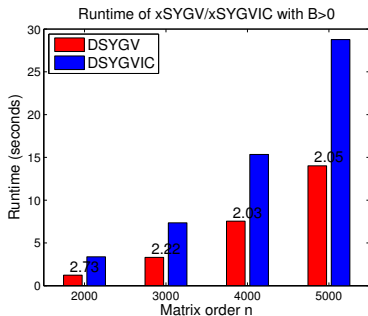
where $R_1 = \text{diag}((D^{(0)})^{-1/2}, I)$

xSYGVIC – Phase I

3. Early exit B is ε -well-conditioned. $A - \lambda B$ is regular and has n ε -stable eigenpairs (Λ, X) :
- ▶ $A^{(1)}U = U\Lambda$ (xSYEV).
 - ▶ $X = Q_1 R_1 U$

xSYGVIC – Phase I: performance profile

- ▶ Test matrices $A = Q_A D_A Q_A^T$ and $B = Q_B D_B Q_B^T$ where
 - ▶ Q_A, Q_B are random orthogonal matrices;
 - ▶ D_A is diagonal with $-1 < D_A(i, i) < 1, i = 1, \dots, n$;
 - ▶ D_B is diagonal with $0 < \varepsilon < D_B(i, i) < 1, i = 1, \dots, n$;
- ▶ 12-core on an Intel "Ivy Bridge" processor (Edison@NERSC)



xSYGVIC – Phase II

1. Compute the eigendecomposition of (2,2)-block $A_{22}^{(2)}$ of $A^{(1)}$ (xSYEV):

$$A_{22}^{(2)} = Q_{22}^{(2)T} A_{22}^{(1)} Q_{22}^{(2)} = \begin{matrix} & n_3 & n_4 \\ n_3 & D^{(2)} & \\ n_4 & & E^{(2)} \end{matrix}$$

where eigenvalues are ordered such that $|d_{11}^{(2)}| \geq |d_{22}^{(2)}| \geq \dots \geq |d_{n_2 n_2}^{(2)}|$, and elements of $E^{(2)}$ are smaller than $\varepsilon |d_{11}^{(2)}|$.

2. Set $E^{(2)} = 0$, and update $A^{(1)}$ and $B^{(1)}$:

$$A^{(2)} = Q_2^T A^{(1)} Q_2, \quad B^{(2)} = Q_2^T B^{(1)} Q_2$$

where $Q_2 = \text{diag}(I, Q_{22}^{(2)})$.

3. Early exit When $A_{22}^{(1)}$ is a ε -well-conditioned matrix. $A - \lambda B$ is regular and has n_1 ε -stable eigenpairs (A, X) :
 - ▶ $A^{(2)}U = B^{(2)}UA$ (Schur complement and xSYEV)
 - ▶ $X = Q_1 R_1 Q_2 U$.

xSYGVIC – Phase II (backup)

$$A^{(2)}U = B^{(2)}U\Lambda \quad (1)$$

where

$$A^{(2)} = \begin{matrix} & \begin{matrix} n_1 & n_2 \end{matrix} \\ \begin{matrix} n_1 \\ n_2 \end{matrix} & \begin{bmatrix} A_{11}^{(2)} & A_{12}^{(2)} \\ A_{12}^{(2)T} & D^{(2)} \end{bmatrix} \end{matrix} \quad \text{and} \quad B^{(2)} = \begin{matrix} & \begin{matrix} n_1 & n_2 \end{matrix} \\ \begin{matrix} n_1 \\ n_2 \end{matrix} & \begin{bmatrix} I & \\ & 0 \end{bmatrix} \end{matrix}$$

. Let

$$U = \begin{matrix} & n_1 \\ \begin{matrix} n_1 \\ n_2 \end{matrix} & \begin{bmatrix} U_1 \\ U_2 \end{bmatrix} \end{matrix}$$

The eigenvalue problem (1) becomes

$$\begin{aligned} F^{(2)}U_1 &= \left(A_{11}^{(2)} - A_{12}^{(2)}(D^{(2)})^{-1}A_{12}^{(2)T} \right) U_1 = U_1\Lambda \quad (\text{xSYEV}) \\ U_2 &= -(D^{(2)})^{-1}(A_{12}^{(2)})^T U_1 \end{aligned}$$

xSYGVIC – Phase II: performance profile

Accuracy:

1. If $B \geq 0$ has n_2 zero eigenvalues:
 - ▶ xSYGV stops, the Cholesky factorization of B could not be completed.
 - ▶ xSYGVIC successfully computes $n - n_2$ ε -stable eigenpairs.
2. If B has n_2 small eigenvalues about δ , both xSYGV and xSYGVIC “work”, but produce different quality numerically.¹
 - ▶ $n = 1000, n_2 = 100, \delta = 10^{-13}$ and $\varepsilon = 10^{-12}$.

	Res1	Res2
DSYGV	3.5e-8	1.7e-11
DSYGVIC	9.5e-15	7.1e-12

- ▶ $n = 1000, n_2 = 100, \delta = 10^{-15}$ and $\varepsilon = 10^{-12}$.

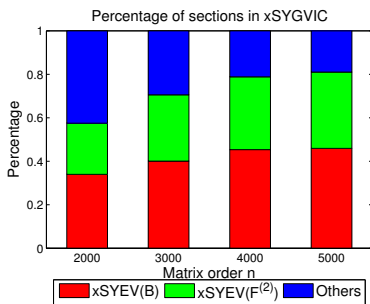
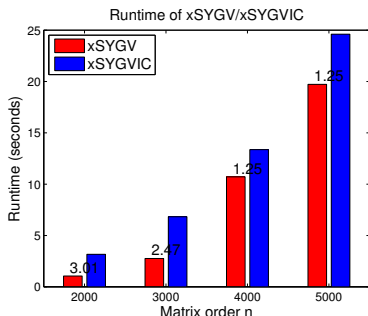
	Res1	Res2
DSYGV	3.6e-6	1.8e-10
DSYGVIC	1.3e-16	6.8e-14

¹Res1 = $\|A\hat{X} - B\hat{X}\hat{\Lambda}\|_F / (n\|A\|_F \|\hat{X}\|_F)$ and
Res2 = $\|\hat{X}^T B \hat{X} - I\|_F / (\|B\|_F \|\hat{X}\|_F^2)$.

xSYGVIC – Phase II: performance profile

Timing:

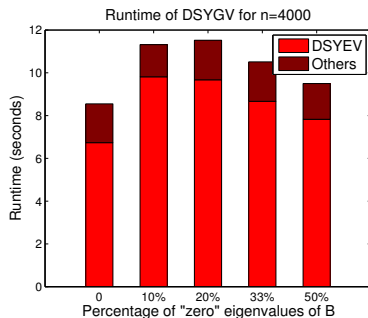
- ▶ Test matrices $A = Q_A D_A Q_A^T$ and $B = Q_B D_B Q_B^T$ where
 - ▶ Q_A, Q_B are random orthogonal matrices;
 - ▶ D_A is diagonal with $-1 < D_A(i, i) < 1, i = 1, \dots, n$;
 - ▶ D_B is diagonal with $0 < D_B(i, i) < 1, i = 1, \dots, n$ and n_2/n
 $D_B(i, i) < \varepsilon$.
- ▶ 12-core on an Intel "Ivy Bridge" processor (Edison@NERSC)



xSYGVIC – Phase II: performance profile

Why is the overhead ratio of xSYGVIC lower?

- ▶ Performance of xSYGV varies depending on the percentage of “zero” eigenvalues of B .
- ▶ For example, for $n = 4000$ on a 12-core processor execution:



xSYGVIC – Phase III

1. $A^{(2)}$ and $B^{(2)}$ can be written as 3 by 3 blocks:

$$A^{(2)} = \begin{matrix} & \begin{matrix} n_1 & n_3 & n_4 \end{matrix} \\ \begin{matrix} n_1 \\ n_3 \\ n_4 \end{matrix} & \begin{bmatrix} A_{11}^{(2)} & A_{12}^{(2)} & A_{13}^{(2)} \\ A_{12}^{(2)T} & D^{(2)} & \\ A_{13}^{(2)T} & & 0 \end{bmatrix} \end{matrix} \quad \text{and} \quad B^{(2)} = \begin{matrix} & \begin{matrix} n_1 & n_3 & n_4 \end{matrix} \\ \begin{matrix} n_1 \\ n_3 \\ n_4 \end{matrix} & \begin{bmatrix} I & & \\ & 0 & \\ & & 0 \end{bmatrix} \end{matrix}$$

where $n_3 + n_4 = n_2$.

2. Reveal the rank of $A_{13}^{(2)}$ by QR decomposition with pivoting:

$$A_{13}^{(2)} P_{13}^{(3)} = Q_{13}^{(3)} R_{13}^{(3)}$$

where

$$R_{13}^{(3)} = \begin{matrix} & n_4 \\ \begin{matrix} n_4 \\ n_5 \end{matrix} & \begin{bmatrix} A_{14}^{(3)} \\ 0 \end{bmatrix} \end{matrix}$$

xSYGVIC – Phase III

3. Final exit When $n_1 > n_4$ and $A_{13}^{(2)}$ is full rank,² then $A - \lambda B$ is regular and has $n_1 - n_4$ ε -stable eigenpairs (Λ, X) :
- ▶ $A^{(3)}U = B^{(3)}U\Lambda$
 - ▶ $X = Q_1 R_1 Q_2 Q_3 U$.

²All the other cases either lead $A - \lambda B$ to be “singular” or “regular but no finite eigenvalues”.

xSYGVIC – Phase III (backup)

$$A^{(3)}U = B^{(3)}U\Lambda \quad (2)$$

- Update

$$A^{(3)} = Q_3^T A^{(2)} Q_3 \quad \text{and} \quad B^{(3)} = Q_3^T B^{(2)} Q_3$$

where

$$Q_3 = \begin{matrix} & n_1 & n_3 & n_4 \\ \begin{matrix} n_1 \\ n_3 \\ n_4 \end{matrix} & \begin{bmatrix} Q_{13}^{(3)} & & \\ & I & \\ & & P_{13}^{(3)} \end{bmatrix} \end{matrix}$$

- Write $A^{(3)}$ and $B^{(3)}$ as 4×4 blocks:

$$A^{(3)} = \begin{matrix} & n_4 & n_5 & n_3 & n_4 \\ \begin{matrix} n_4 \\ n_5 \\ n_3 \\ n_4 \end{matrix} & \begin{bmatrix} A_{11}^{(3)} & A_{12}^{(3)} & A_{13}^{(3)} & A_{14}^{(3)} \\ (A_{12}^{(3)})^T & A_{22}^{(3)} & A_{23}^{(3)} & 0 \\ (A_{13}^{(3)})^T & (A_{23}^{(3)})^T & D^{(2)} & 0 \\ (A_{14}^{(3)})^T & 0 & 0 & 0 \end{bmatrix} \end{matrix}, \quad B^{(3)} = \begin{matrix} & n_4 & n_5 & n_3 & n_4 \\ \begin{matrix} n_4 \\ n_5 \\ n_3 \\ n_4 \end{matrix} & \begin{bmatrix} I & & & \\ & I & & \\ & & 0 & \\ & & & 0 \end{bmatrix} \end{matrix},$$

where $n_1 = n_4 + n_5$ and $n_2 = n_3 + n_4$.

xSYGVIC – Phase III (backup)

► Let

$$U = \begin{matrix} & n_5 \\ n_4 & \left[\begin{array}{c} U_1 \\ U_2 \\ U_3 \\ U_4 \end{array} \right] \\ n_5 & \\ n_3 & \\ n_4 & \end{matrix}$$

then the eigenvalue problem (2) becomes:

$$\begin{aligned} U_1 &= 0 \\ \left(A_{22}^{(3)} - A_{23}^{(3)} (D^{(3)})^{-1} A_{23}^{(3)T} \right) U_2 &= U_2 \Lambda \quad (\mathbf{xSYEV}) \\ U_3 &= -(D^{(2)})^{-1} A_{23}^{(3)T} U_2 \\ U_4 &= -(A_{14}^{(3)})^{-1} \left(A_{12}^{(3)} U_2 + A_{13}^{(3)} U_3 \right) \end{aligned}$$

xSYGVIC – Phase III: performance profile

Test case (Fix-Heiberger'72)

1. Consider 8×8 matrices:

$$A = Q^T H Q \quad \text{and} \quad B = Q^T S Q,$$

where

$$H = \begin{bmatrix} 6 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 5 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 4 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 3 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

and

$$S = \text{diag}[1, 1, 1, 1, \delta, \delta, \delta, \delta]$$

As $\delta \rightarrow 0$, $\lambda = 3, 4$ are the only stable eigenvalues of $A - \lambda B$.

xSYGVIC – Phase III: performance profile

2. The computed eigenvalues when $\delta = 10^{-15}$:

λ_i	<code>eig(A,B,'chol')</code>	DSYGV	DSYGVIC($\epsilon = 10^{-12}$)
1	-3.334340289520080e+07	-0.3229260685047438e+08	0.3000000000000001e+01
2	-3.138309114827999e+07	-0.3107213627119420e+08	0.3999999999999999e+01
3	2.99999998949329e+00	0.2957918878610765e+01	
4	3.99999999513074e+00	0.4150528124449937e+01	
5	3.138309673669569e+07	0.3107214204558684e+08	
6	3.334340856015300e+07	0.3229261357421688e+08	
7	1.077763236890488e+15	0.1004773743630529e+16	
8	2.468473375420724e+15	0.2202090698823234e+16	

An algebraic reformulation

(with H. Xie)

Symmetric semi-definite pencil

Symmetric semi-definite pencil:

$$A - \lambda B, \quad \text{with } A^T = A \text{ and } B^T = B \geq 0$$

Symmetric semi-definite pencil

Canonical form. There exists a nonsingular matrix $W \in \mathbb{R}^{n \times n}$ such that

$$W^T A W = \begin{matrix} & \begin{matrix} 2n_1 & r & n_2 & s \end{matrix} \\ \begin{matrix} 2n_1 \\ r \\ n_2 \\ s \end{matrix} & \begin{bmatrix} \Lambda_1 & & & \\ & \Lambda_2 & & \\ & & \Lambda_3 & \\ & & & 0 \end{bmatrix} \end{matrix} \text{ and } W^T B W = \begin{matrix} & \begin{matrix} 2n_1 & r & n_2 & s \end{matrix} \\ \begin{matrix} 2n_1 \\ r \\ n_2 \\ s \end{matrix} & \begin{bmatrix} \Omega_1 & & & \\ & I & & \\ & & 0 & \\ & & & 0 \end{bmatrix} \end{matrix}$$

where

$$\Lambda_1 = I_{n_1} \otimes K, \Lambda_2 = \text{diag}(\lambda_i), \Lambda_3 = \text{diag}(\pm 1), \Omega_1 = I_{n_1} \otimes T$$

and

$$K = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad T = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

Algebraic reformulation

Theorem [Xie and B.'16]. Suppose that the symmetric semi-definite pencil $A - \lambda B$ is regular and simultaneously diagonalizable with a congruence transformation. Given a symmetric positive definite matrix $H \in \mathbb{R}^{k \times k}$ and $\mu \in \mathbb{R}$, let us define

$$\tilde{A} = A + \mu(AZ)H(AZ)^T, \quad \tilde{B} = B + (AZ)H(AZ)^T,$$

where $Z \in \mathbb{R}^{n \times k}$ spans the nullspace of B . Then³

- (1) The pencil $\tilde{A} - \lambda \tilde{B}$ is symmetric definite,
- (2) $\lambda(\tilde{A}, \tilde{B}) = \lambda_f(A, B) \cup \lambda(\mu H + (Z^T A Z)^{-1}, H)$

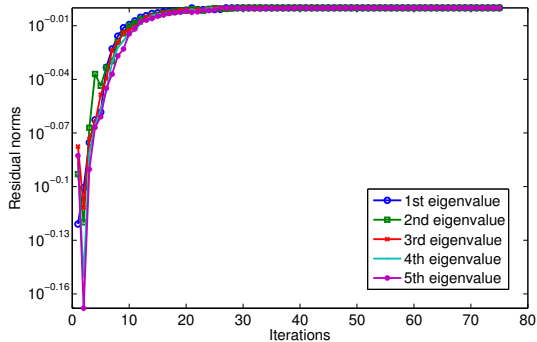
By appropriately chosen H and μ , one can compute the k smallest (finite) eigenvalues of $A - \lambda B$ directly, say by LOBPCG.

³Notations: $\lambda(A, B)$ denotes the set of eigenvalues of a pencil $A - \lambda B$. $\lambda_f(A, B)$ denotes the set of all finite eigenvalues of $A - \lambda B$.

Algebraic reformulation

A test case from structure dynamics

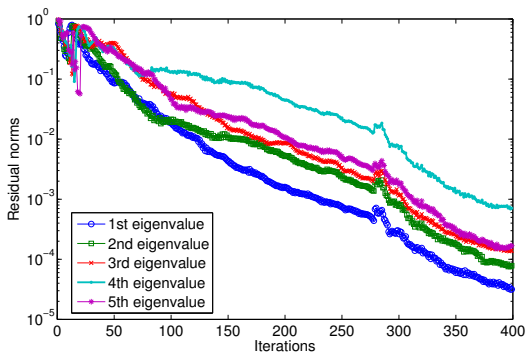
LOBPCG:



Algebraic reformulation

A test case from structure dynamics

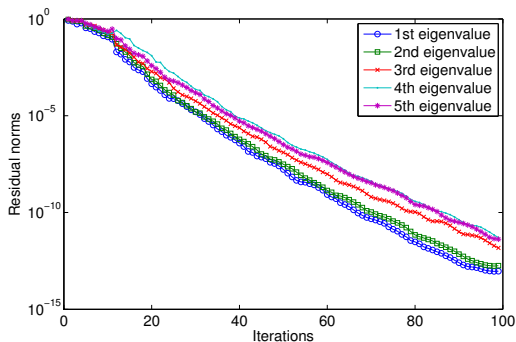
Algebraic reformulation + LOBPCG without preconditioning



Algebraic reformulation

A test case from structure dynamics

Algebraic reformulation + LOBPCG with preconditioning



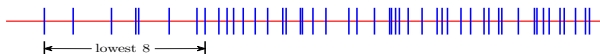
A locally accelerated BPSD (LABPSD)

Ill-conditioned GSEP

GSEP:

$$Hu_i = \lambda_i Su_i$$

1. Matrices H and S are ill-conditioned
e.g., $\text{cond}(H), \text{cond}(S) = \mathcal{O}(10^{10})$
2. Share a *near-nullspace* $\text{span}\{V\}$
e.g., $\|HV\| = \|SV\| = \mathcal{O}(10^{-4})$
3. No obvious spectrum gap between eigenvalues of interest and the rest
e.g.,



PSD*id*

- ▶ **PSD***ed*: Preconditioned Steepest Descent with implicit deflation
- ▶ Assume the first $i - 1$ eigenpairs $(\lambda_1, u_1), \dots, (\lambda_{i-1}, u_{i-1})$ computed, and denote $U_{i-1} = [u_1, u_2, \dots, u_{i-1}]$.
- ▶ **PSD***id* computes the i -th eigenpair (λ_i, u_i)
 - 0 initialize $(\lambda_{i;0}, u_{i;0})$
 - 1 for $j = 0, 1, \dots$ until convergence
 - 2 compute $r_{i;j} = Hu_{i;j} - \lambda_{i;j}Su_{i;j}$
 - 3 precondition $p_{i;j} = -K_{i;j}r_{i;j}$
 - 4 $(\gamma_i, w_i) = \text{RR}(H, S, Z)$, where $Z = [U_{i-1} \ u_{i;j} \ p_{i;j}]$
 - 5 $\lambda_{i;j+1} = \gamma_i, u_{i;j+1} = Zw_i$
- ▶ ..., [Faddeev/Faddeeva'63],..., [Longsine/McCormick'80] for $K_{i;j} = I$,
...

PSD *id* assumptions

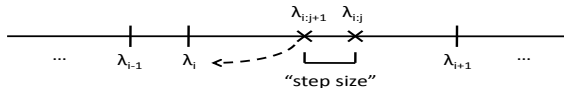
1. initialize $u_{i;0}$ such that $U_{i-1}^H S u_{i;0} = 0$ and $\|u_{i;0}\|_S = 1$
2. $\lambda_{i;0} = \rho(u_{i;0})$, Rayleigh quotient
3. the preconditioners $K_{i;j}$ are *effective positive definite*, namely,

$$K_{i;j}^d \equiv (U_{i-1}^c)^T S K_{i;j} S U_{i-1}^c > 0,$$

where $U_{i-1}^c = [u_i, u_{i+1}, \dots, u_n]$.

PSD *id* properties

1. Z is of full column rank
2. $U_{i-1}^H S u_{i;j+1} = 0$ and $\|u_{i;j+1}\|_S = 1$
3. $\lambda_i \leq \lambda_{i;j+1} < \lambda_{i;j}$
4. $\lambda_{i;j} - \lambda_{i;j+1} \geq \sqrt{g^2 + \phi^2} - g = \text{"step size"} > 0,$



5. $p_{i;j} = -K_{i;j} r_{i;j}$ is an *ideal search direction* if $p_{i;j}$ satisfies

$$U^T S(u_{i;j} + p_{i;j}) = (\times, \dots, \times, \xi_i, 0, \dots, 0)^T \quad \text{and} \quad \xi_i \neq 0. \quad (3)$$

It implies that $\lambda_{i;j+1} = \lambda_i$.

PSD *id* convergence

If $\lambda_i < \lambda_{i;0} < \lambda_{i+1}$ and $\sup_j \text{cond}(K_{i;j}^d) = q < \infty$, then the sequence $\{\lambda_{i;j}\}_j$ is strictly decreasing and bounded from below by λ_i , i.e.,

$$\lambda_{i;0} > \lambda_{i;1} > \cdots > \lambda_{i;j} > \lambda_{i;j+1} > \cdots \geq \lambda_i$$

and as $j \rightarrow \infty$,

1. $\lambda_{i;j} \rightarrow \lambda_i$
2. $u_{i;j}$ converges to u_i *directionally*.

$$\|r_{i;j}\|_{S^{-1}} = \|Hu_{i;j} - \lambda_{i;j}Su_{i;j}\|_{S^{-1}} \rightarrow 0$$

PSD *id* convergence rate

Let $\epsilon_{i;j} = \lambda_{i;j} - \lambda_i$, then

$$\epsilon_{i;j+1} \leq \left[\frac{\Delta + \tau \sqrt{\theta_{i;j} \epsilon_{i;j}}}{1 - \tau(\sqrt{\theta_{i;j} \epsilon_{i;j}} + \delta_{i;j} \epsilon_{i;j})} \right]^2 \epsilon_{i;j}$$

provided that the i -th approximate eigenvalue $\lambda_{i;j}$ is **localized**, i.e.

$$\tau(\sqrt{\theta_{i;j} \epsilon_{i;j}} + \delta_{i;j} \epsilon_{i;j}) < 1,$$

where

- ▶ $\Delta = \frac{\Gamma - \gamma}{\Gamma + \gamma}$ and $\tau = \frac{2}{\Gamma + \gamma}$
- ▶ $\delta_{i;j} = \|S^{\frac{1}{2}} K_{i;j} S^{\frac{1}{2}}\|$ and $\theta_{i;j} = \|S^{\frac{1}{2}} K_{i;j} M K_{i;j} S^{\frac{1}{2}}\|$

Γ and γ are largest and smallest pos. eigenvalues of $K_{i;j} M$ and $M = P_{i-1}^H (H - \lambda_i S) P_{i-1}$ and $P_{i-1} = I - U_{i-1} U_{i-1}^H S$

PSD *id* convergence rate, cont'd

Remarks:

1. If $K_{i;j} = I$, the convergence of SD proven in [Faddeev/Faddeeva'63,..., Longside/McCormick'80, ...]
2. If $i = 1$ and $K_{1;j} = K > 0$, it is Samokish's theorem (1958), which is first and still sharpest quantitative analysis [Ovtchinnikov'06].
3. Asymptotically,

$$\epsilon_{i;j+1} \leq \left[\Delta + \mathcal{O}(\epsilon_{i;j}^{1/2}) \right]^2 \epsilon_{i;j}$$

4. Optimal $K_{i;j}$: $\Delta = 0 \rightsquigarrow$ quadratic conv.
5. Semi-optimal $K_{i;j}$: $\Delta + \tau \sqrt{\theta_{i;j} \epsilon_{i;j}} \rightarrow 0 \rightsquigarrow$ superlinear conv.
6. (Semi-)optimality depends on the eigenvalue distribution of $K_{i;j}M$

Locally accelerated preconditioner

Consider the preconditioner

$$\widehat{K}_{i;j} = (H - \beta_{i;j}S)^{-1} \quad \text{with} \quad \beta_{i;j} = \lambda_{i;j} - c\|r_{i;j}\|_{S^{-1}}$$

If

$$0 < \Delta_{i;j} < \min\left\{\frac{1}{4}\Delta_i^2, 0.1\right\} \quad \text{and} \quad c > 3\sqrt{\Delta_{i;j}}.$$

Then

1. $K_{i;j}$ is effective positive definite
2. $\lambda_{i;j}$ is localized
3. $\Delta + \tau\sqrt{\theta_{i;j}\epsilon_{i;j}} \rightarrow 0$

Therefore, $\widehat{K}_{i;j}$ is asymptotically optimal

PSD $id \rightsquigarrow$ LABPSD = Locally Accelerated BPSD

```
0 Initialize  $U_{m+\ell;0} = [u_{1;0} \ u_{2;0} \ \dots \ u_{m+\ell;0}]$ 
1  $(\Gamma, W) = \text{RR}(H, S, U_{m+\ell;0})$ 
2 update  $\Lambda_{m+\ell;0} = \Gamma$  and  $U_{m+\ell;0} = U_{m+\ell;0}W$ 
3 for  $j = 0, 1, \dots$ , do
4     compute  $R = HU_{m;j} - SU_{m;j}\Lambda_{m;j} \equiv [r_{1;j} \ r_{2;j} \ \dots \ r_{m;j}]$ 
5     if  $\text{Res}[\Lambda_{m;j}, U_{m;j}] = \max_{1 \leq i \leq m} \text{Res}[\lambda_{i;j}, u_{i;j}] \leq \tau_{\text{eig}}$ , break
6     for  $i = 1, 2, \dots, m$ 
7         if  $\lambda_{i;j}$  is localized, then solve  $(H - \lambda_{i;j}S)p_{i;j} = -r_{i;j}$  for  $p_{i;j}$ 
8          $(\Gamma_{m+\ell}, W_{m+\ell}) = \text{RR}(H, S, Z)$ , where  $Z = [U_{m+\ell;j} \ P_j]$ 
9         update  $\Lambda_{m+\ell;j+1} = \Gamma_{m+\ell}$  and  $U_{m+\ell;j+1} = ZW_{m+\ell}$ 
9     end
10 return  $\{(\lambda_{i;j}, u_{i;j})\}_{i=1}^m$ 
```

Note: A “global” preconditioner $\approx (H - \sigma S)^{-1}$ can be used to accelerate the “localization” and convergence of step 6.

Numerical example 1: Harmonic1D

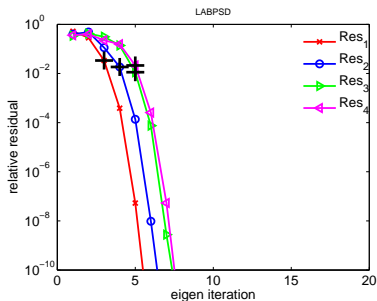
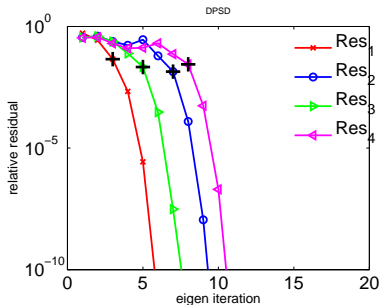
- ▶ PUFFE discretization for harmonic oscillator in 1D
- ▶ $n = 112$ for 6-digit accuracy of 4 smallest eigenvalues $\lambda_1, \lambda_2, \lambda_3, \lambda_4$
- ▶ H and S are ill-conditioned

$$\text{cond}(H) = 8.79 \times 10^{10} \quad \text{and} \quad \text{cond}(S) = 2.00 \times 10^{12}$$

- ▶ H and S share a *near-nullspace* $\text{span}\{V\}$

$$\|HV\| = \|SV\| = O(10^{-5}) \quad \text{and} \quad \dim(V) = 17$$

- ▶ All computed $\hat{\lambda}_1, \hat{\lambda}_2, \hat{\lambda}_3, \hat{\lambda}_4$ have 6-digit accuracy.



Numerical example 2: CeAl-PUFE

- ▶ Metallic, triclinic CeAl, particularly challenging [Cai, B., Pask, Sukumar'13]
- ▶ $n = 5336$ from PUFE discretization of the Kohn-Sham equation
- ▶ H and S are ill-conditioned

$$\text{cond}(H) = 1.16 \times 10^{10} \quad \text{and} \quad \text{cond}(S) = 2.57 \times 10^{11}$$

- ▶ H and S share a *near-nullspace* $\text{span}\{V\}$

$$\|HV\| = \|SV\| = O(10^{-4}) \quad \text{and} \quad \dim(V) = 1000$$

